

# Analysis of CNN working with logical decision functions in the task of computer tomography images recognition

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Problem formulation

Task and Data

Current state of the work

Analysis CNN in lung cancer recognition(previous semester)

# Problem formulation

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# Problem

## General statement

Assume  $X$  set of objects  $x$ .  $Y$  is set of labels,  $X^d \in X$ - random sample of size  $d$ .  $y^* : X \rightarrow Y$  goal function known on  $X^d$ . Need to build decision function  $f(X) \rightarrow Y$  minimizing the probability of error.

## More accurate formulation

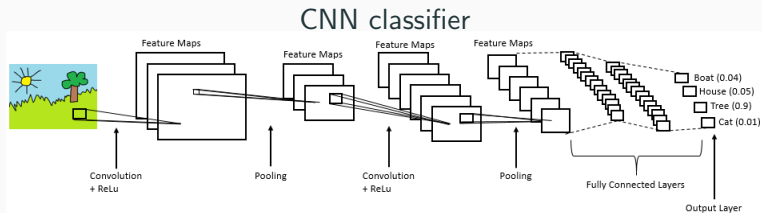
- $X$  is set of objects and  $Y$  is set of labels,  $X$  corresponds with  $Y$ , the task is: Using elements in CNN functional set of tool build feature representation of object? which most optimal in classification task by logical functions.
- Based build feature representation of object, develop logical predictive model with high interpretive decision making process and high quality predictive ability.

## **Task and Data**

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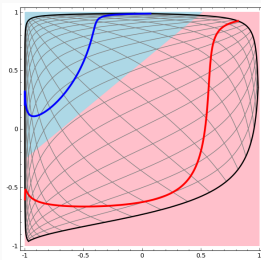
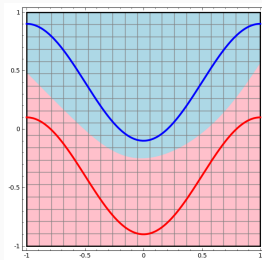
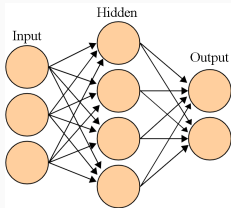
# Tasks and Data

- The task: two types stroke recognition by Computer tomography images.
- Data: CT images in DICOM format of human brain with/(without) pathologies.
- Labels: Ichemic stroke, hemorrhagic stroke, none.
- Expected result: recognition model with CNN module for feature extracting with interpretative decision making process using logical recognition functions and vision based explanation.



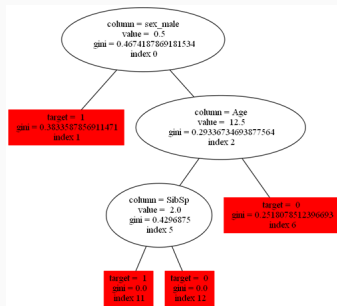
- Feature extractor: CNN block
- Classifier: MLP block with softmax
- CNN learned weights in optimal way for MLP classifier after:  
 $f(x) = \operatorname{argmin}(L(\operatorname{MLP}(f(x))))$
- MLP with hidden layers transform input feature space to be linearly separable

# MLP data transformation





# Decision Tree



Example of decision making ( $x_k \rightarrow y$ ):

$(f_1(x_k) < M_i) \text{ and } (f_2(x_k)) < (M_j) \rightarrow y_k$ , where  $f_i$  - features of  $x_k$ ,  
 $y_k$  - predicted label

## CNN with decision tree as classifier

Take feature vector from last conv. layer of pretrained network and build decision tree on given data

- it give as weakly Analysis of feature importance in decision making process
- problem: this features can be not optimal for decision tree type of model.

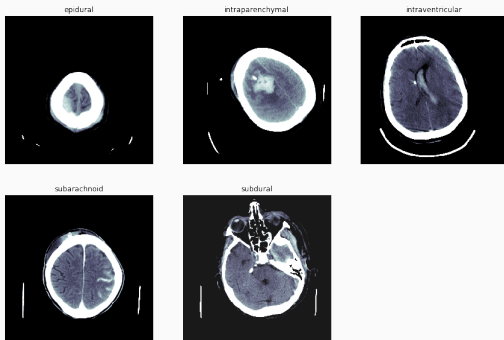
Solution - train CNN with decision tree as classifier, if CNN and DT will be train simultaneously, learned features are optimal for DT, and decision tree is optimal for learned features.

- optimal learned features for logical recognition function
- strong CNN features analysis
- main problem - decision tree learning process is not differentiable

## **Current state of the work**

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# Task and Data

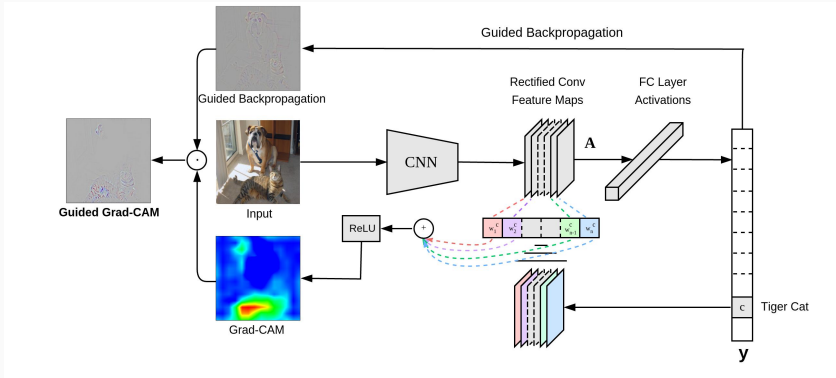


- RSNA Intracranial Hemorrhage Detection (multi label classification)
- Five Hemorrhage subtypes (epidural, intraparenchymal, intraventricular, subarachnoid, subdural)
- 674258 raw Dicom images for train with class imbalance

# Intracranial Hemorrhage Detection

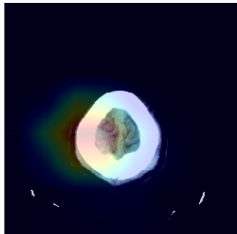
- EfficientNet B2 with one hidden layer MLP, binary cross entropy loss
- Trainig: 3 epoch
- Result
  - Test loss 0.23
  - Test AUC = 0.95
  - Test Acc = 0.97

# GradCAM

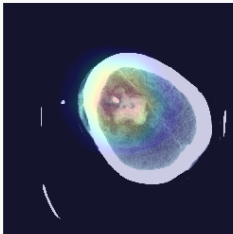


# GradCAM

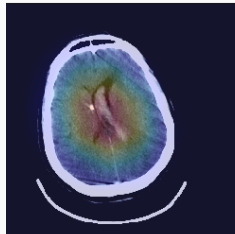
epidural



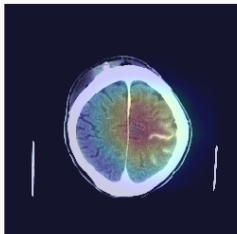
intraparenchymal



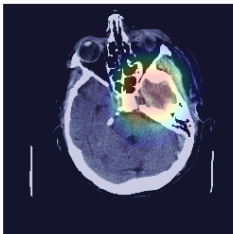
intraventricular



subarachnoid



subdural



# Tree Regularization CNN training



# **Analysis CNN in lung cancer recognition(previous semester)**

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# Data preposition

- Crop tumours from images with 50x50 resolution
- There are a total of 551065 annotations.
  - 1351 positive(cancer)
  - 549714(non-cancer)
- So there big class imbalance for training
- Augment positive class by rotating images by 90,180 and 270 degrees.

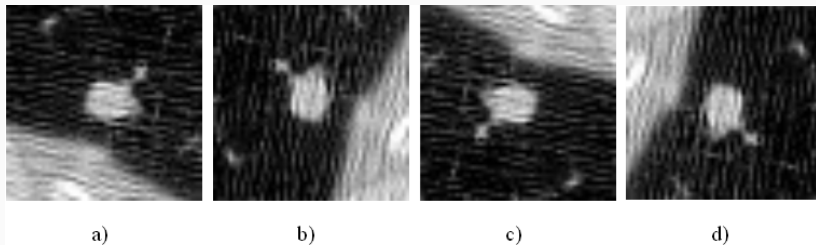


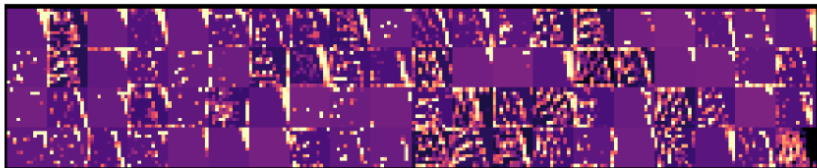
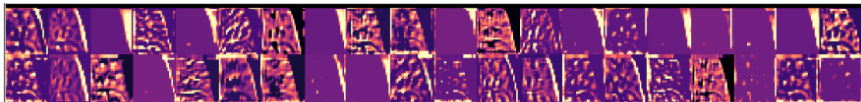
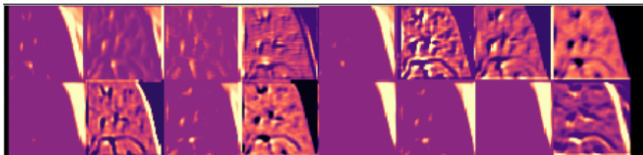
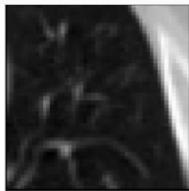
Figure 2. Augmentation: a) - original, b) - 90 degree rotation c) - 180 degree rotation, d) - 270 degree rotation

# CNN model training

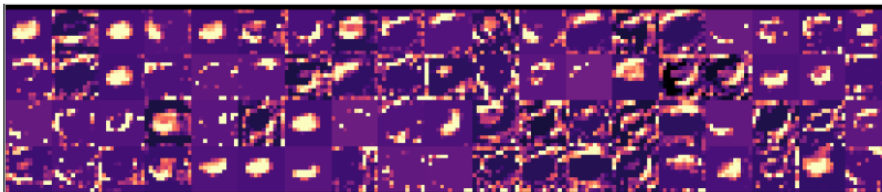
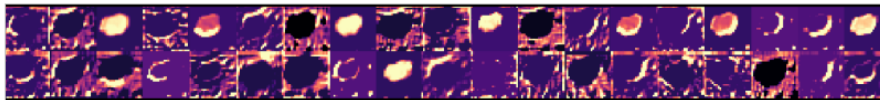
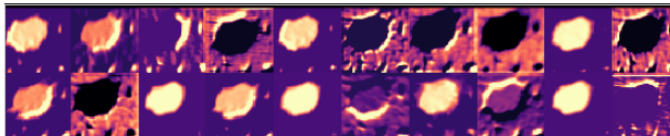
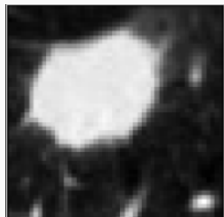
- Train (7722):
  - cancer 3380
  - non-cancer 4342
- Test (2251):
  - cancer 1073
  - non-cancer 1178

Input layer shape = (batch_size,50,50,1)		
Conv2D 20 (5x5) + relu		
Maxpooling (2,2)		
Conv2D 40 (3x3) + relu		
MaxPooling (2,2)		
Conv2D 80 (3,3) + relu		
Maxpooling (2,2)		
Flatten		
Dence(180) + relu		
Dence(2) + softmax		
sample	accuracy	loss
Train	0.982906	0.050968
Test	0.9253665	0.210678

## Actuation's visualization: benign tumor



# Actuation's visualizing:malignant tumor



## Filter Visualization

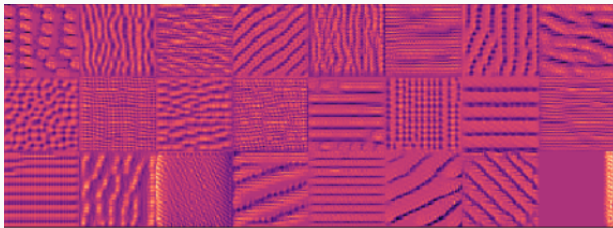
Assume  $I$  - origin image,  $F_l^c$  - filter  $c$  of layer  $l$ . We want to get image  $I'$  with maximal activation of filter  $F_l^c$ . In this way we train our images by this process:

$$I' = I + \frac{dL(F_l^c, I')}{dI'} \text{rate},$$

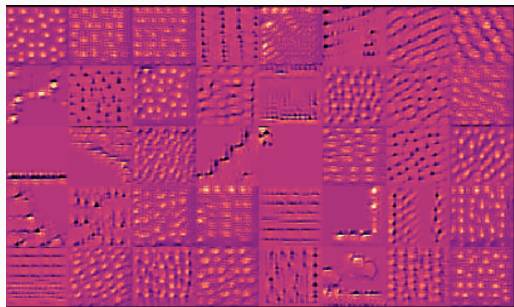
where  $L(F_l^c, I') = \frac{1}{n*m} \sum_{i,j} A_{i,j}^{l,c}$  We change our image  $I$  in gradient of loss of  $F_l^c$



**Figure 1:** conv layer 1



**Figure 2:** conv layer2



**Figure 3:** conv layer3

## Covariation “Style” matrix

$I$  – input image,  $A_{i,j}^{c,l}$  activation in position  $(i, j)$  of filter  $c$  of layer  $l$  for image  $I$ . Covariation between two filter defined as:

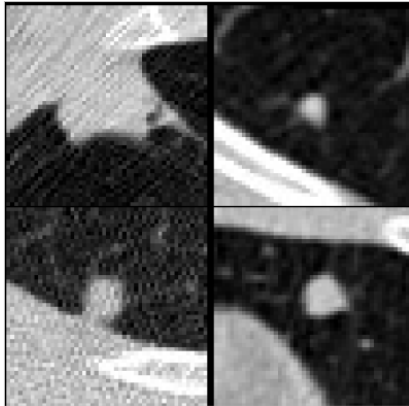
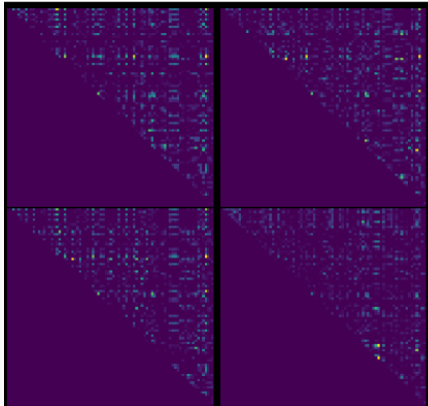
$$\text{cov}(f_1, f_2) = \frac{\sum_{i,j}^n ((A_{i,j}^{f1} - \text{mean}(A_{i,j}^{f1}))((A_{i,j}^{f2} - \text{mean}(A_{i,j}^{f2}))))}{n^2}$$

where  $n$  – size of feature map.

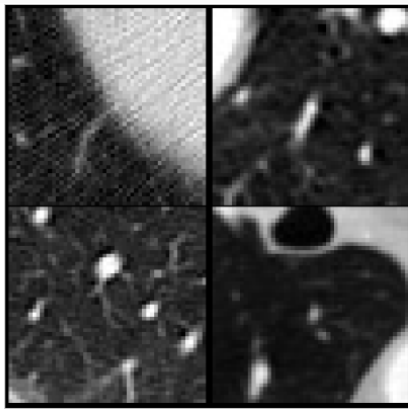
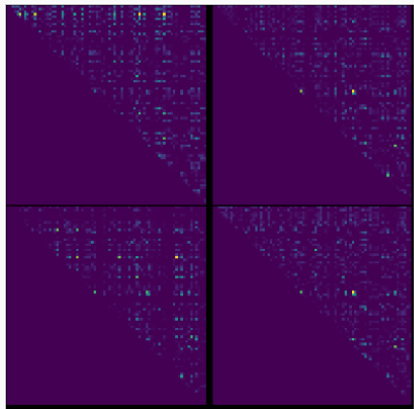
malignant tumour	benign tumour
(28, 40)	<u>(34,56)</u>
<b>(57, 76)</b>	<b>(56,73)</b>
<u>(34, 56)</u>	(34,35)
<b>(56, 73)</b>	<b>(56,76)</b>
(40, 68)	(53,76)



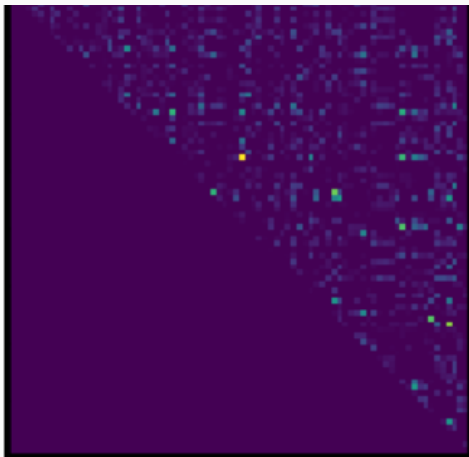
## Covariation matrix:malignant tumor



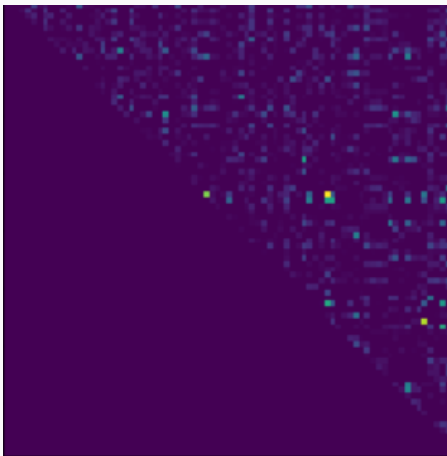
## Covariation matrix: benign tumor



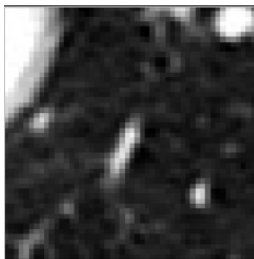
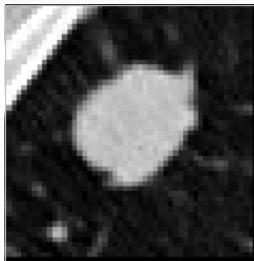
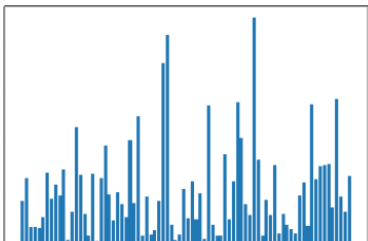
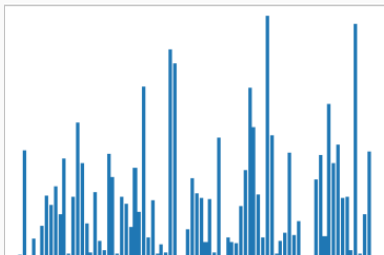
## Averaged covariation:malignant tumor



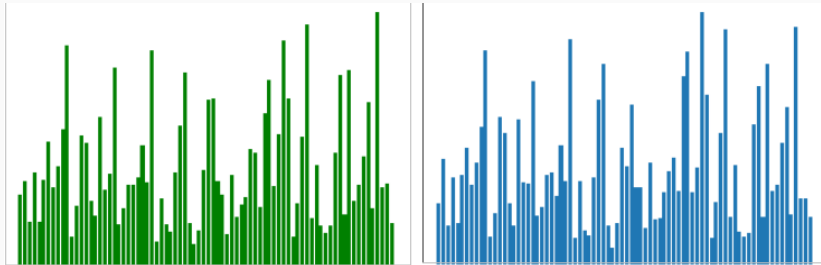
## Averaged covariation:benign tumor



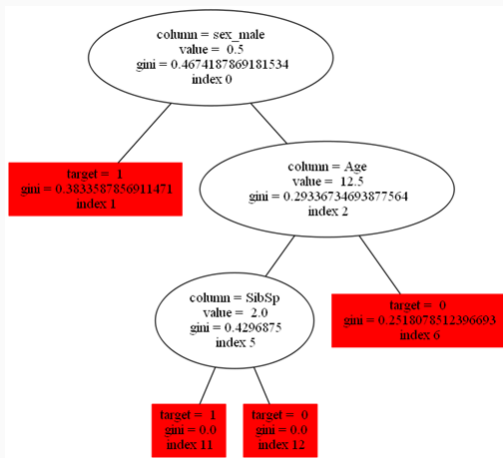
# Layer distribution



# Layer distribution



# Decision tree



# Decision tree

Method	Depth = 3	Depth = 4	Depth = 5	Depth = 6
DT + max activations	0.7209	0.7526	0.79056	0.81122
DT + average activations	0.75370	0.76472	0.76610	0.78091
DT + full layer	0.88219	0.867034	0.89700	0.887357
DT + maxpooling	0.85291	0.848432	0.88804	0.88012



- Visualization the most understandable form but cannot be explained mathematically
- For effective using a decision tree model we need to use spatial information of features activation with values of activation
- In feature work different methods of analysis and visualizations will be combined and used to build decision tree to explain decision making of CNN.

Thanks for attention