Deep learning-based Machine Vision for the Task of Grasping Chemical Hardware

Машинное зрение на основе глубокого обучения для захвата химического оборудования

Coursework

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Dataset and data annotation

- Captured 60 images with a dimension of 640 by 480 pixels
- Data split ratio was 80/20
 - 48 train images
 - 12 test images
- Used LabelMe [1] for object annotations. Save into COCO JSON



Objects of interest	Number of annotations of train dataset			
Black rubber	36			
Empty hole	289			
Grasp	36			
Hand	54			
Shaker body	39			
Stand	50			
Tube throat	129			
Total	633			

[1] https://github.com/wkentaro/labelme

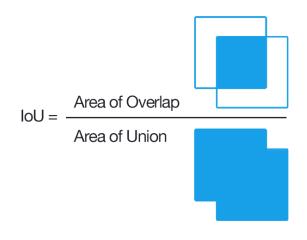
Training

- Applied MMDetection for solving instance segmentation task [2]
- Used "cascade_mask_rcnn_x101_64x4d_fpn_1x_coco"
 - Box average precision of 44.7
 - Model type: Cascade Mask R-CNN
 - Backbone: ResNeXt-101
- Applied a checkpoint for faster training
 - "cascade_mask_rcnn_x101_64x4d_fpn_1x_coco_20200203-9a2db89d.pth"
- Epochs: 100
- Learning rate: 0.02
- GPU Tesla V100
- Training took about 20 minutes

^[2] https://github.com/open-mmlab/mmdetection/tree/master/configs/cascade_rcnn

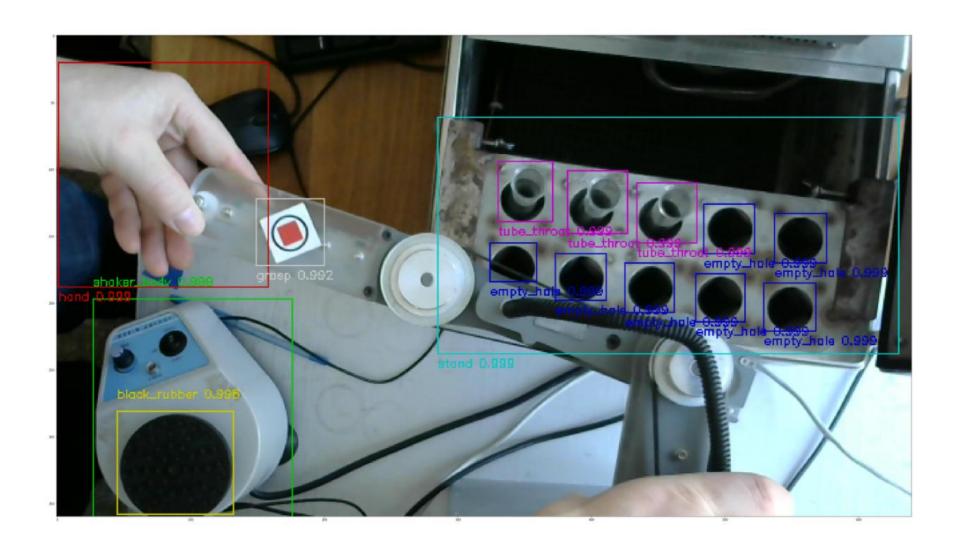
Model Evaluation – Intersection-over-union (IOU)

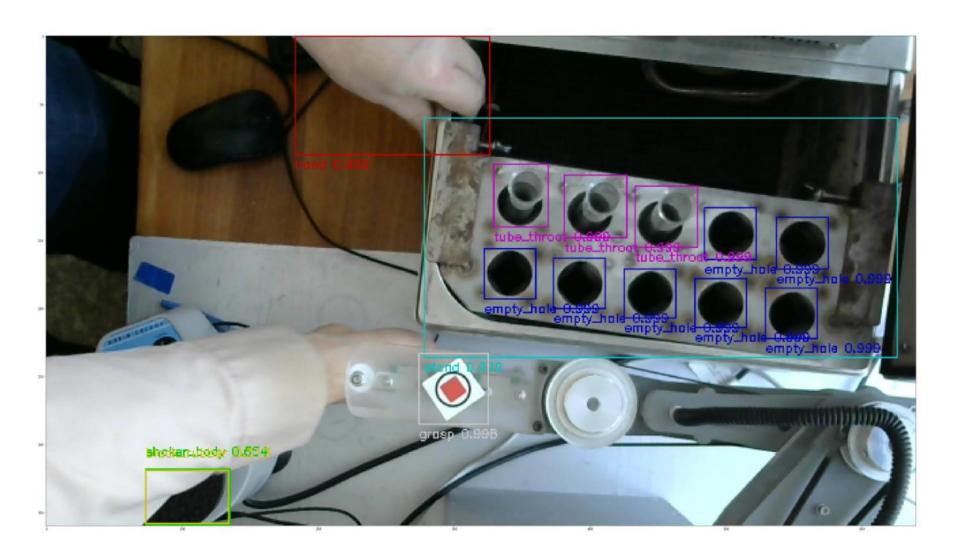
Objects	IOU ratio		
Black rubber	0.902		
Empty hole	0.929		
Grasp	0.933		
Hand	0.920		
Shaker body	0.838		
Stand	0.950		
Tube throat	0.915		



Source: https://www.pyimagesearch.com/2016/11/07/intersection-over-union-iou-for-object-detection/

- Threshold value of 0.3
- The result of object detection was greatly satisfied
- Shaker body showed poorer score than other objects because of, in the test images, their surface was partially blocked by other objects







Conclusion

- MMDetection provides numerous model inference codes and trained weights, that facilitates the users to perform tasks
- We obtained the intersection-over-union scores over 0.9 on most objects
- The shaker body received the lowest score of 0.838 among the others. It can be improved with larger train dataset

Contributions

- We show that instance segmentation task with deep learning approach can be performed and yielded satisfied results on MMDetection, an alternative tool apart of Tensorflow or Pytorch
- The chemical apparatus detectors can be developed further and applied with robotic arms such as SCARA (Selective Compliance Assembly Robot Arm) in order to automate the tasks

References

- [1] https://github.com/wkentaro/labelme
- [2] https://github.com/open-mmlab/mmdetection/tree/master/configs/cascade_rcnn